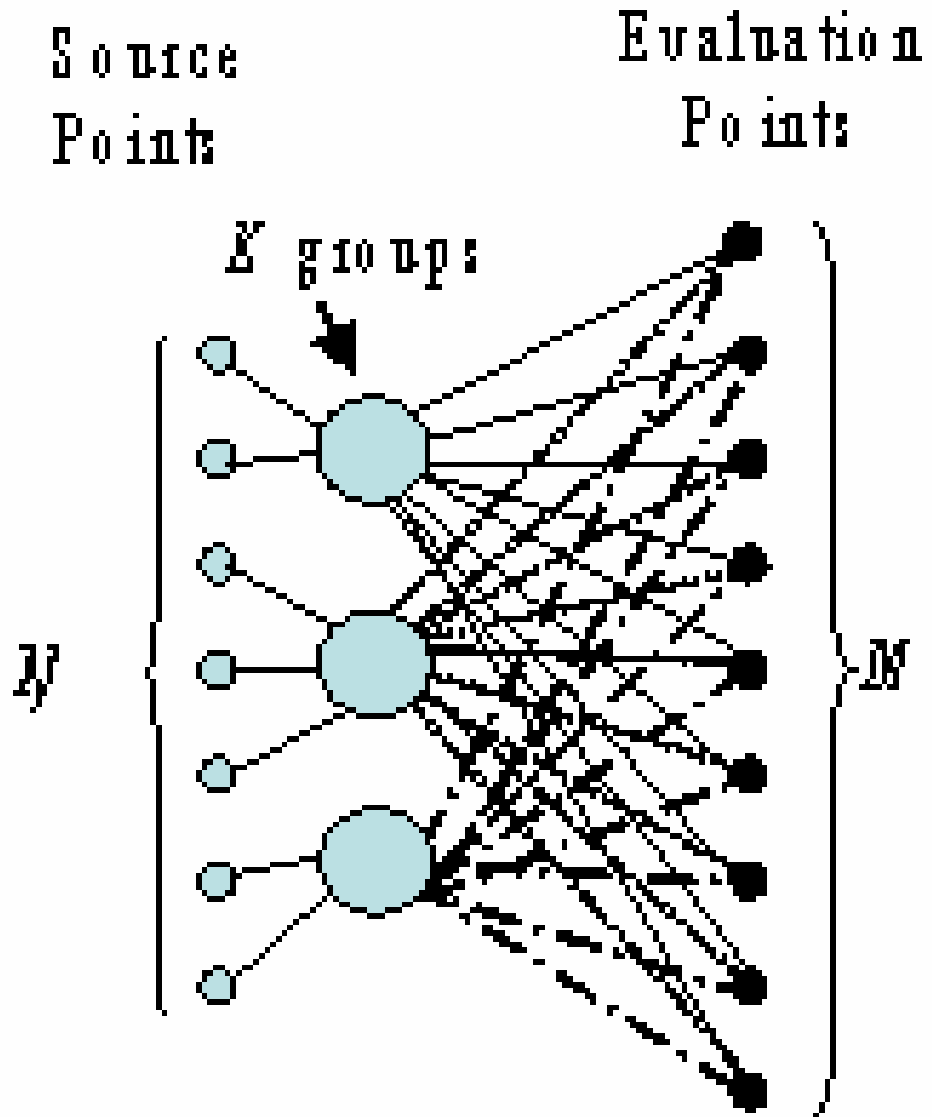


# Lecture 17:CMSC 878R/AMSC698R

# Exam – Q3

- Question 3
- $N$  sources
- Need to form  $S$  expansion for each about the center (one of the  $K$  boxes)
- Cost is  $NP$
- Each box has  $N/K$  sources
- Need to sum up the  $K$  expansions
- Evaluate these at  $M$  points
- So we have  $KMP$  operations



# Problem 3

- Take  $M = N$
- In the neighboring boxes we have to do direct evaluation (as the S expansion is not valid)
- There are  $3^d - 1$  neighbors for each of the  $K$  boxes
- Each box contains  $N/K$  sources and  $M/K$  evaluation points
- Direct evaluation requires  $(MN/K^2)$  for one pair
- Total  $(3^d - 1)(MN/K^2)K$
- Putting it together we have
- $F(K, N) = NP + (3^d - 1)N^2/K + KNP$

First term always smaller than 3<sup>rd</sup>

$$dF/dK = -(3^d - 1)N^2/K^2 + NP = 0$$

# Question 3

$$(3^d - 1)N^2/K^2 = NP$$

$$K = (3^d - 1)^{1/2} (N/P)^{1/2} \simeq N^{1/2}$$

$$F(K, N) = NP + (3^d - 1)^{1/2} N^{3/2} P^{1/2} + (3^d - 1)^{1/2} N^{3/2} P^{1/2} = O(N^{3/2})$$

# Question 4

- Bit interleaving

- Given box number 127

$$127=64+32+16+8+4+2+1$$
$$=2^6+2^5+2^4+2^3+2^2+2^1+2^0$$

$$127_{\{10\}}=1111111_2$$

- Given quadtree, so the dimension is 2
- Start from the end
- 1111 and 111
- So we can de-interleave as  $\{0111,1111\}$  and so the number of the box is  $\{7,15\}$
- So the neighborhood is  $\{6,14\} \{7,14\} \{8,14\} \{6,15\} \{7,15\}, \{8,15\} \{6,16\} \{7,16\}, \{8,16\}$
- However for 16 we require 5 bits (10000), and we are at level 4

# Question 4

- So the neighborhood is  $\{6,14\} \{7,14\} \{8,14\} \{6,15\} \{7,15\}, \{8,15\}$
- Go back to binary
- $\{0110,1110\} \{0111,1110\} \{1000,1110\} \{0110,1111\} \{0111,1111\} \{1000,1111\}$
- Interleave
- $\{01111100\} \{01111110\} \{11010100\} \{01111101\} \{01111111\} \{11010101\}$
- $2^6+2^5+2^4+2^3+2^2=64+32+16+8+4=124$
- $2^6+2^5+2^4+2^3+2^2+2^1=64+32+16+8+4+2=126$
- $2^7+2^4+2^2+2^0=128+64+16+4=212$
- $64+32+16+8+4+1=125$
- $64+32+16+8+4+2+1=127$
- $128+64+16+4+1=213$

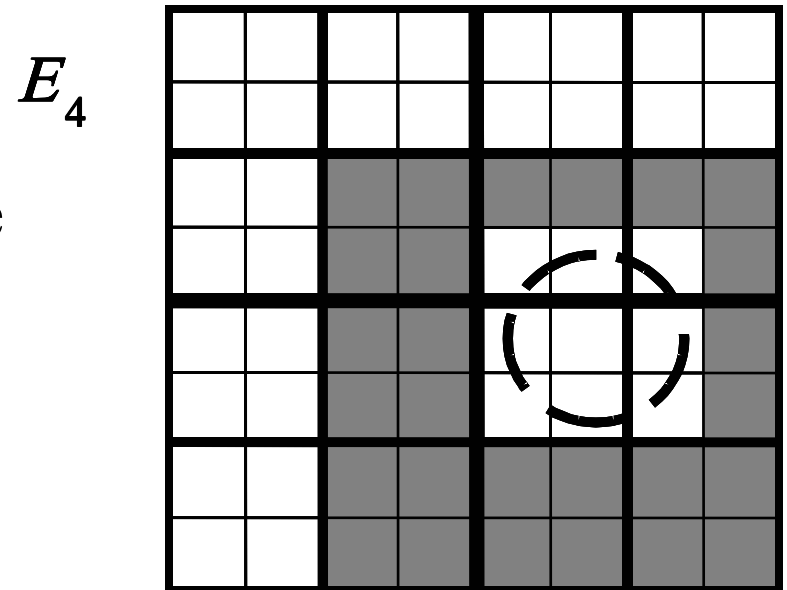
# DOWNWARD PASS

- Starting from level 2, build an  $R$  expansion in boxes where  $R$  expansion is valid

$$\Phi_4^{(n,l)}(\mathbf{y}) = \tilde{\mathbf{D}}^{(n,l)} \circ \mathbf{R}(\mathbf{y} - \mathbf{x}_c^{(n,l)}),$$

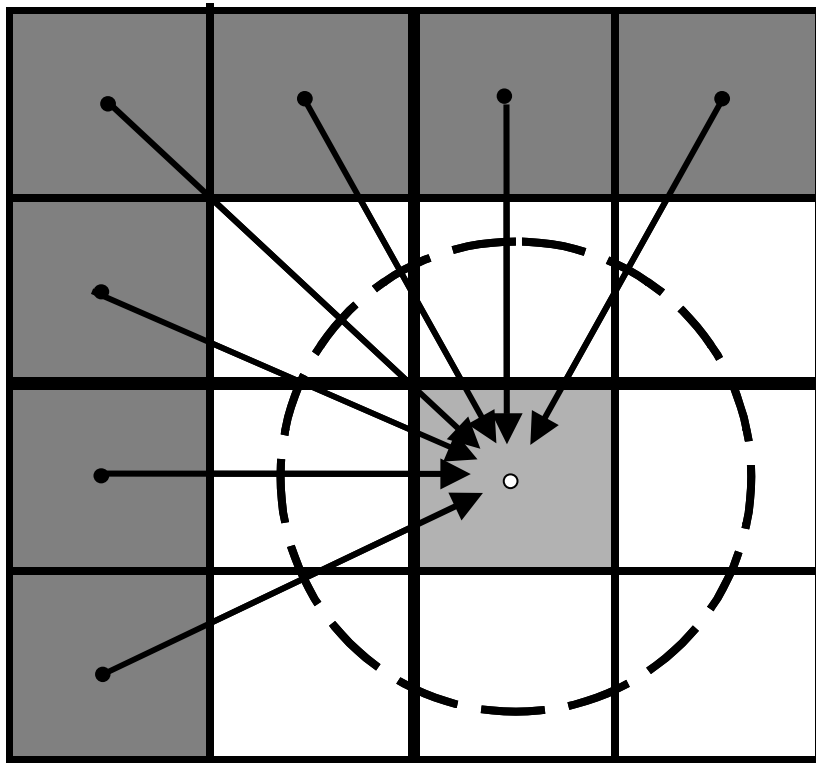
$$\tilde{\mathbf{D}}^{(n,l)} = \sum_{m \in I_4(n,l)} (\mathbf{S}|\mathbf{R}) \left( \mathbf{x}_c^{(n,l)} - \mathbf{x}_c^{(m,l)} \right) \mathbf{C}^{(m,l)}.$$

- Must to do  $S|R$  translation
- The  $S$  expansion is not valid in boxes immediately surrounding the current box
- So we must exclude boxes in the  $E_4$  neighborhood

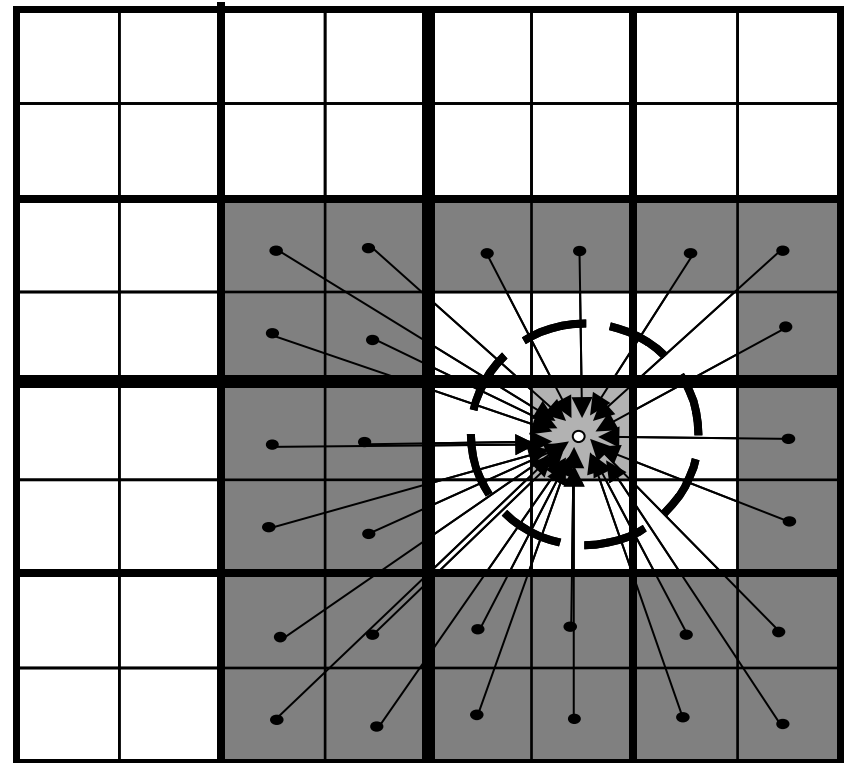


# Downward Pass. Step 1.

Level 2:

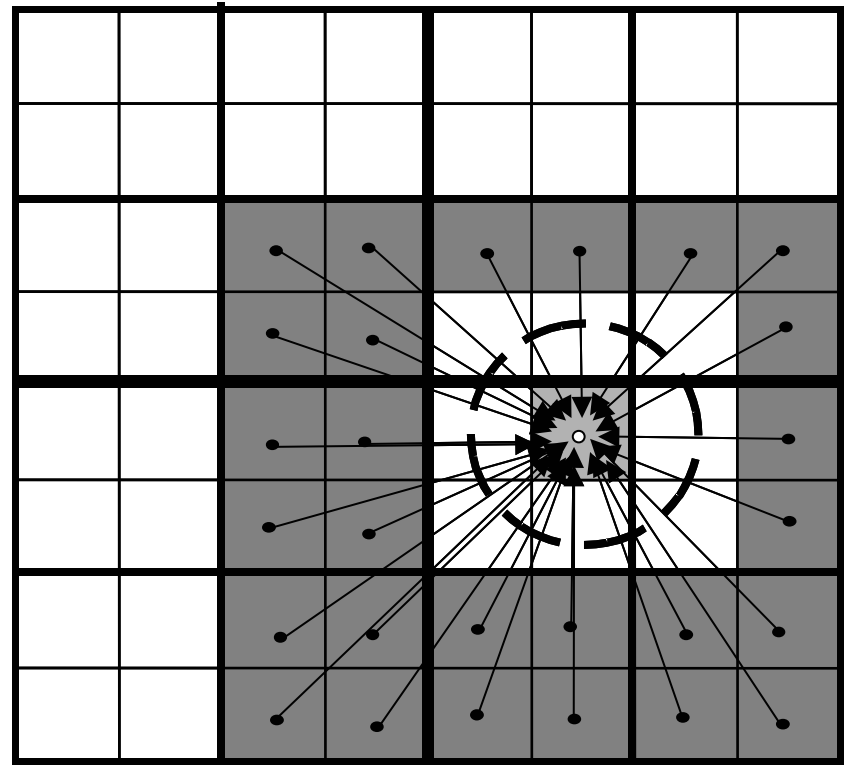


Level 3:



# Downward Pass. Step 1.

THIS MIGHT BE  
THE MOST EXPENSIVE  
STEP OF THE ALGORITHM



# Projects

- Jaynarayan Sitaraman: fast evaluation of Biot Savart velocity fields.
  - 3-D. No equation to solve ...
- Ankur and Vikas: Kernel methods via FMM
  - Explore iterative methods for eigen-value problems
  - Solve some toy problems
- Changjiang Yang: Fast Gauss Transform based on Taylor series
- Ali Zandifar, Sernam Lin: Thin plate spline fitting for 2-D problems
- Azam El-Halfy, Kexue Liu: fitting of RBFs in 3-D for interpolation (graphics and vision applications)

- Jun Shen – 2-D fast vortex method
- Zhihui Tang: Helmholtz equation and the FMM

# Format of Project

- November 14 – due problem statement and approach of the project
  - What is the problem? Does it require matrix vector product or solution of some linear system? Prior Work?
  - What is the function  $\Phi$ ? What is the S expansion? What is the R expansion? What are the S|S, S|R and R|R translation matrices?
- November 28 – due progress report
  - Direct solution of some sample problems
  - FMM solution
- December 5 – 15 minute talk and final report



# Project Ideas

- Your research
- Scattered data interpolation in 1-D, 2-D and 3-D using RBFs
- <ftp://ftp.stat.wisc.edu/pub/wahba/interf/rootpar2r.pdf>
- The fast gauss transform and its performance in multiple dimensions
- Accelerating the BEM for the Helmholtz equation in 2D and/or 3D

- Accelerating the BEM for the Laplace equation in 2D and/or 3D
- An animation of the MLFMM ... HTML or JAVA animations of a 2-D problem (see the site on spatial data structures on Hanan Samet's site)
- Fast Fourier Transforms based on the FMM

- Eigenvalue problems using the FMM  
(<http://www.cs.utk.edu/~dongarra/etemplates/>) Using the FMM with Rayleigh
- Compressible 2-D vortex method ...
- Others (particularly would like to see problems from your research, or problems which generalize the FMM to operators which are distributive (not necessarily products))

# FMM CMSC 878R/AMSC 698R

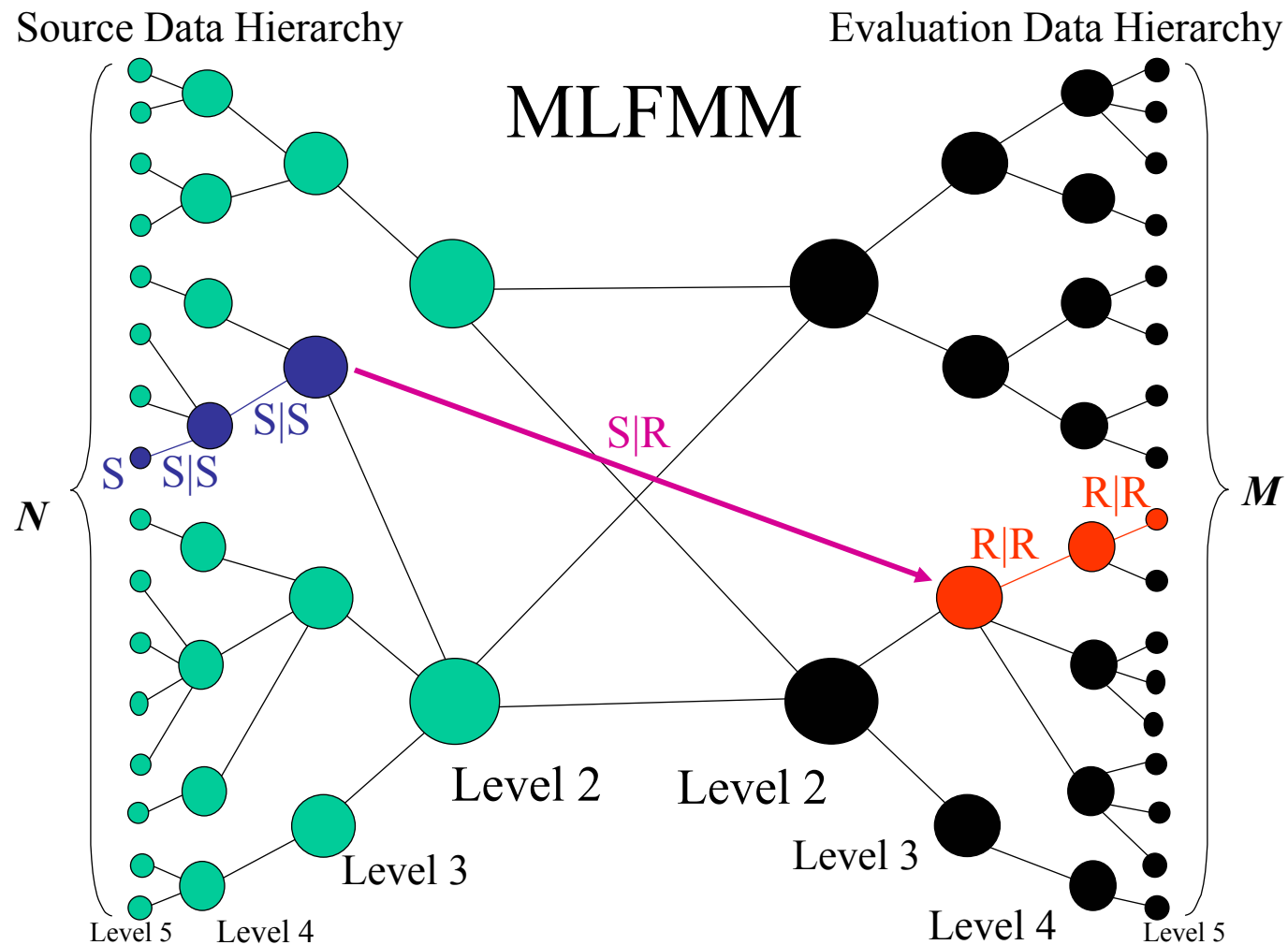
## Lecture 17

# Outline

- Error Bounds of MLFMM
  - A scheme for error evaluation;
- Example problem
  - S-expansion error;
  - S|S-translation error;
  - S|R-translation error;
  - R|R-translation error.
- Error and Neighborhoods

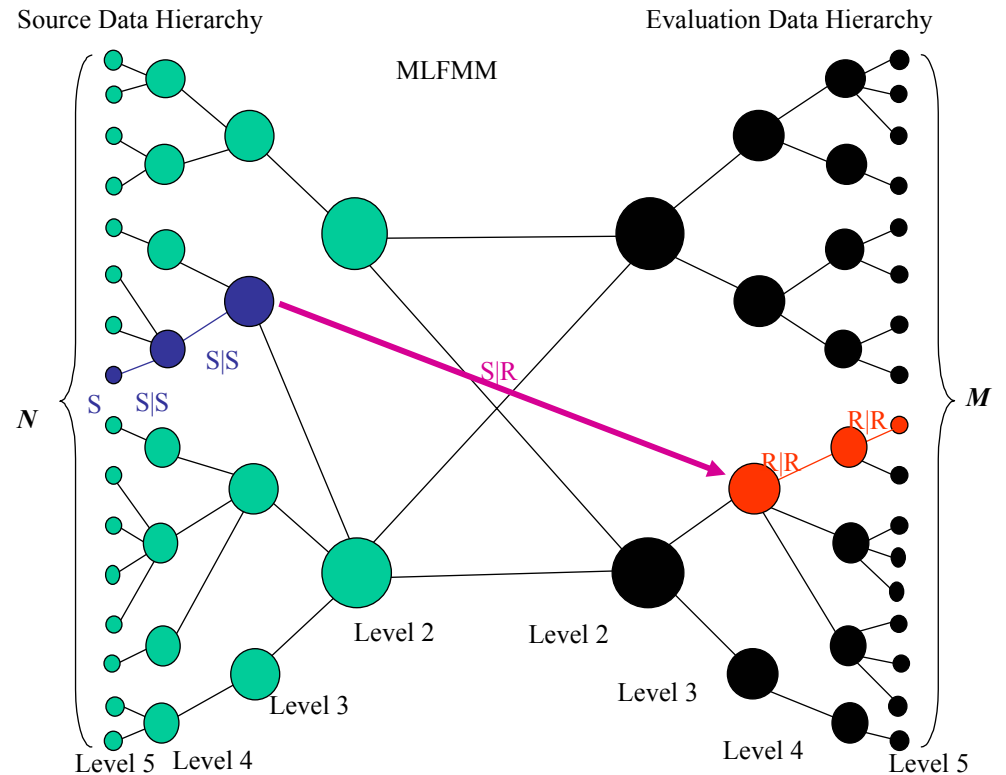
# A scheme for error evaluation (1)

(How one source contributes to one evaluation points)



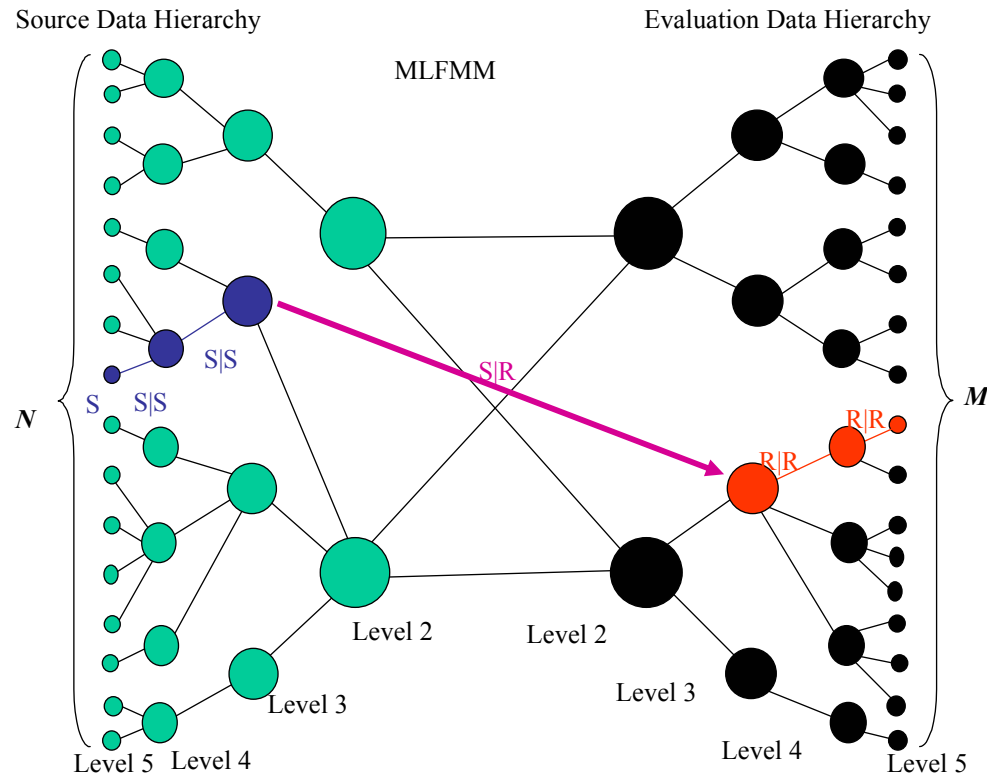
# A scheme for error evaluation (2)

$$\begin{aligned}
 \Phi(\mathbf{y}, \mathbf{x}_k) &= \sum_{m=0}^{\infty} C_m^{(L)}(\mathbf{x}_k, \mathbf{x}_*^{(L)}) S_m(\mathbf{y} - \mathbf{x}_*^{(L)}) = \mathbf{C}^{(L)}(\mathbf{x}_k, \mathbf{x}_*^{(L)}) \cdot \mathbf{S}(\mathbf{y} - \mathbf{x}_*^{(L)}) \\
 &= \mathbf{C}^{(L-1)}(\mathbf{x}_k, \mathbf{x}_*^{(L-1)}) \cdot \mathbf{S}(\mathbf{y} - \mathbf{x}_*^{(L-1)}) \\
 &= \dots = \mathbf{C}^{(l)}(\mathbf{x}_k, \mathbf{x}_*^{(l)}) \cdot \mathbf{S}(\mathbf{y} - \mathbf{x}_*^{(l)}) \\
 &= \mathbf{D}^{(l)}(\mathbf{x}_k, \mathbf{y}_*^{(l)}) \cdot \mathbf{R}(\mathbf{y} - \mathbf{y}_*^{(l)}) \\
 &= \mathbf{D}^{(l+1)}(\mathbf{x}_k, \mathbf{y}_*^{(l+1)}) \cdot \mathbf{R}(\mathbf{y} - \mathbf{y}_*^{(l+1)}) \\
 &= \dots = \mathbf{D}^{(L)}(\mathbf{x}_k, \mathbf{y}_*^{(L)}) \cdot \mathbf{R}(\mathbf{y} - \mathbf{y}_*^{(L)}).
 \end{aligned}$$



# A scheme for error evaluation (3)

$$\begin{aligned}
 D^{(L)}(\mathbf{x}_k, \mathbf{y}_*^{(L)}) &= (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)}) D^{(L-1)}(\mathbf{x}_k, \mathbf{y}_*^{(L-1)}) \\
 &= [(\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)}) \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L-1)} - \mathbf{y}_*^{(L-2)})] D^{(L-2)}(\mathbf{x}_k, \mathbf{y}_*^{(L-2)}) \\
 &= \dots = [(\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)}) \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L-1)} - \mathbf{y}_*^{(L-2)}) \circ \dots \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(l+1)} - \mathbf{y}_*^{(l)})] D^{(l)}(\mathbf{x}_k, \mathbf{y}_*^{(l)}) \\
 &= [(\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)}) \circ \dots \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(l+1)} - \mathbf{y}_*^{(l)}) \circ (\mathbf{S}|\mathbf{R})(\mathbf{y}_*^{(l)} - \mathbf{x}_*^{(l)})] C^{(l)}(\mathbf{x}_k, \mathbf{x}_*^{(l)}) \\
 &= [(\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)}) \circ \dots \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(l+1)} - \mathbf{y}_*^{(l)}) \circ (\mathbf{S}|\mathbf{R})(\mathbf{y}_*^{(l)} - \mathbf{x}_*^{(l)}) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(l)} - \mathbf{x}_*^{(l+1)})] C^{(l+1)}(\mathbf{x}_k, \mathbf{x}_*^{(l+1)}) \\
 &= \dots \\
 &= [(\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)}) \circ \dots \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(l+1)} - \mathbf{y}_*^{(l)}) \circ (\mathbf{S}|\mathbf{R})(\mathbf{y}_*^{(l)} - \mathbf{x}_*^{(l)}) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(l)} - \mathbf{x}_*^{(l+1)}) \circ \dots \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(L-1)} - \mathbf{x}_*^{(L)})] C^{(L)}(\mathbf{x}_k, \mathbf{x}_*^{(L)})
 \end{aligned}$$



# A scheme for error evaluation (4)

Consider computation of the final coefficients with  $p$ -truncated matrices

$$\begin{aligned}
 \mathbf{D}^{(L)}(\mathbf{x}_k, \mathbf{y}_*^{(L)}) &= [\text{Pr}(p) \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)}) \circ \text{Pr}(p)] \circ \dots \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(l+1)} - \mathbf{y}_*^{(l)}) \circ \text{Pr}(p)] \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{R})(\mathbf{y}_*^{(l)} - \mathbf{x}_*^{(l)}) \circ \text{Pr}(p)] \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(l)} - \mathbf{x}_*^{(l+1)}) \circ \text{Pr}(p)] \circ \dots \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(L-2)} - \mathbf{x}_*^{(L-1)}) \circ \text{Pr}(p)] \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(L-1)} - \mathbf{x}_*^{(L)}) \circ \text{Pr}(p)] \mathbf{C}^{(L)}(\mathbf{x}_k, \mathbf{x}_*^{(L)})
 \end{aligned}$$

These truncation operators can be skipped! ( $\text{Pr}^2 = \text{Pr}$ )

So:

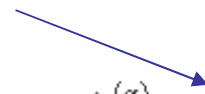
$$\begin{aligned}
 \mathbf{D}^{(L)}(\mathbf{x}_k, \mathbf{y}_*^{(L)}) &= [\text{Pr}(p) \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(L)} - \mathbf{y}_*^{(L-1)})] \circ \dots \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(l+1)} - \mathbf{y}_*^{(l)})] \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{R})(\mathbf{y}_*^{(l)} - \mathbf{x}_*^{(l)})] \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(l)} - \mathbf{x}_*^{(l+1)})] \circ \dots \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(L-2)} - \mathbf{x}_*^{(L-1)})] \circ \\
 &\quad [\text{Pr}(p) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(L-1)} - \mathbf{x}_*^{(L)})] \circ \text{Pr}(p) \mathbf{C}^{(L)}(\mathbf{x}_k, \mathbf{x}_*^{(L)})
 \end{aligned}$$

# A scheme for error evaluation (5)

$p$ -truncated functions:

$$\begin{aligned}\hat{\Phi}_L(\mathbf{y}, \mathbf{x}_k) &= \hat{\mathbf{C}}^{(L)}(\mathbf{x}_k, \mathbf{x}_*^{(L)}) \cdot \mathbf{S}(\mathbf{y} - \mathbf{x}_*^{(L)}) \\ \hat{\Phi}_{L-1}(\mathbf{y}, \mathbf{x}_k) &= \hat{\mathbf{C}}^{(L-1)}(\mathbf{x}_k, \mathbf{x}_*^{(L-1)}) \cdot \mathbf{S}(\mathbf{y} - \mathbf{x}_*^{(L-1)}) \\ &\dots \\ \hat{\Phi}_l(\mathbf{y}, \mathbf{x}_k) &= \hat{\mathbf{C}}^{(l)}(\mathbf{x}_k, \mathbf{x}_*^{(l)}) \cdot \mathbf{S}(\mathbf{y} - \mathbf{x}_*^{(l)}) \\ \hat{\Psi}_l(\mathbf{y}, \mathbf{x}_k) &= \hat{\mathbf{D}}^{(l)}(\mathbf{x}_k, \mathbf{y}_*^{(l)}) \cdot \mathbf{R}(\mathbf{y} - \mathbf{y}_*^{(l)}) \\ \hat{\Psi}_{l+1}(\mathbf{y}, \mathbf{x}_k) &= \hat{\mathbf{D}}^{(l+1)}(\mathbf{x}_k, \mathbf{y}_*^{(l+1)}) \cdot \mathbf{R}(\mathbf{y} - \mathbf{y}_*^{(l+1)}) \\ &\dots \\ \hat{\Psi}_L(\mathbf{y}, \mathbf{x}_k) &= \hat{\mathbf{D}}^{(L)}(\mathbf{x}_k, \mathbf{y}_*^{(L)}) \cdot \mathbf{R}(\mathbf{y} - \mathbf{y}_*^{(L)}).\end{aligned}$$

The error comes  
only from truncation  
operator



$$\begin{aligned}\hat{\mathbf{C}}^{(\alpha)} &= \Pr(p) \circ (\mathbf{S}|\mathbf{S})(\mathbf{x}_*^{(\alpha)} - \mathbf{x}_*^{(\alpha+1)}) \hat{\mathbf{C}}^{(\alpha+1)}, \quad \alpha = L-1, \dots, l \\ \hat{\mathbf{D}}^{(l)} &= \Pr(p) \circ (\mathbf{S}|\mathbf{R})(\mathbf{y}_*^{(l)} - \mathbf{x}_*^{(l)}) \hat{\mathbf{C}}^{(l)}, \\ \hat{\mathbf{D}}^{(\alpha)} &= \Pr(p) \circ (\mathbf{R}|\mathbf{R})(\mathbf{y}_*^{(\alpha)} - \mathbf{y}_*^{(\alpha+1)}) \hat{\mathbf{C}}^{(\alpha+1)}, \quad \alpha = l, \dots, L-1\end{aligned}$$

# Truncated Translation Theorem

(see Lecture 11)

Let  $\{F_n(\mathbf{y})\}$  and  $\{G_n(\mathbf{y})\}$  be two expansion bases in  $\Omega$ , and the reexpansion series converges everywhere in  $\Omega$  :

$$\forall \mathbf{y} \in \Omega, \quad F_n(\mathbf{y}) = \sum_{m=0}^{\infty} (F|G)_{mn} G_m(\mathbf{y}), \quad n = 0, 1, 2, \dots$$

Let also  $\{A_n\}$  be a set of coefficients, such that the double sum converges absolutely and uniformly in  $\Omega$  :

$$\forall \mathbf{y} \in \Omega, \quad \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} A_n (F|G)_{mn} G_m(\mathbf{y}) = \Phi(\mathbf{y}),$$

$$\forall \epsilon, \exists p(\epsilon), \quad \sum_{n=0}^{\infty} \sum_{m=p}^{\infty} |A_n (F|G)_{mn} G_m(\mathbf{y})| < \epsilon, \quad \sum_{n=p}^{\infty} \sum_{m=0}^{\infty} |A_n (F|G)_{mn} G_m(\mathbf{y})| < \epsilon.$$

Then

$$\left| \Phi(\mathbf{y}) - \sum_{n=0}^{p-1} \sum_{m=0}^{p-1} A_n (F|G)_{mn} G_m(\mathbf{y}) \right| < 2\epsilon.$$

# A scheme for error evaluation (5)

For uniformly and absolutely convergent series:

$$\begin{aligned}
 & \left| \widehat{\Phi}_\alpha(\mathbf{y}, \mathbf{x}_k) - \widehat{\Phi}_{\alpha+1}(\mathbf{y}, \mathbf{x}_k) \right| \\
 &= \left| \sum_{m=0}^{p-1} \widehat{C}_m^{(\alpha)} S_m(\mathbf{y} - \mathbf{x}_*^{(\alpha)}) - \sum_{n=0}^{p-1} \widehat{C}_n^{(\alpha+1)} S_n(\mathbf{y} - \mathbf{x}_*^{(\alpha+1)}) \right| \\
 &= \left| \sum_{m=0}^{p-1} \sum_{n=0}^{p-1} (S|S)_{nm}(\mathbf{x}_*^{(\alpha)} - \mathbf{x}_*^{(\alpha+1)}) \widehat{C}_n^{(\alpha+1)} S_m(\mathbf{y} - \mathbf{x}_*^{(\alpha)}) \right. \\
 &\quad \left. - \sum_{n=0}^{p-1} \widehat{C}_n^{(\alpha+1)} \sum_{m=0}^{\infty} (S|S)_{nm}(\mathbf{x}_*^{(\alpha)} - \mathbf{x}_*^{(\alpha+1)}) S_m(\mathbf{y} - \mathbf{x}_*^{(\alpha)}) \right| \\
 &= \left| \sum_{n=0}^{p-1} \widehat{C}_n^{(\alpha+1)} \sum_{m=p}^{\infty} (S|S)_{nm}(\mathbf{x}_*^{(\alpha)} - \mathbf{x}_*^{(\alpha+1)}) S_m(\mathbf{y} - \mathbf{x}_*^{(\alpha)}) \right| \\
 &\leq \sum_{n=0}^{p-1} \sum_{m=p}^{\infty} \left| \widehat{C}_n^{(\alpha+1)} (S|S)_{nm}(\mathbf{x}_*^{(\alpha)} - \mathbf{x}_*^{(\alpha+1)}) S_m(\mathbf{y} - \mathbf{x}_*^{(\alpha)}) \right| \\
 &< \sum_{n=0}^{\infty} \sum_{m=p}^{\infty} \left| \widehat{C}_n^{(\alpha+1)} (S|S)_{nm}(\mathbf{x}_*^{(\alpha)} - \mathbf{x}_*^{(\alpha+1)}) S_m(\mathbf{y} - \mathbf{x}_*^{(\alpha)}) \right| < \epsilon_{\max}(p).
 \end{aligned}$$

## A scheme for error evaluation (6)

For uniformly and absolutely convergent series it is possible to find such  $\epsilon_{\max}(p)$  that for given minimum(maximum) translation distance the max abs difference between two subsequent functions is smaller than  $\epsilon_{\max}(p)$ .

In this case the total error of FMM does not exceed:

$$FMMError \leq N \left[ \epsilon_{\max}^{(\text{exp})}(p) + (L-2)\epsilon_{\max}^{(S|S)}(p) + \epsilon_{\max}^{(S|R)}(p) + (L-2)\epsilon_{\max}^{(R|R)}(p) \right].$$

$$\lim_{p \rightarrow \infty} \epsilon_{\max}^{(\text{exp})}(p) = 0, \quad \lim_{p \rightarrow \infty} \epsilon_{\max}^{(S|S)}(p) = 0, \quad \lim_{p \rightarrow \infty} \epsilon_{\max}^{(S|R)}(p) = 0, \quad \lim_{p \rightarrow \infty} \epsilon_{\max}^{(R|R)}(p) = 0.$$

If

$$\epsilon(p) = \max \left( \epsilon_{\max}^{(\text{exp})}(p), \epsilon_{\max}^{(S|S)}(p), \epsilon_{\max}^{(S|R)}(p), \epsilon_{\max}^{(R|R)}(p) \right),$$

$$FMMError \leq 2N(L-1)\epsilon(p).$$

# Error of exact $R|R$ , $S|S$ , and $S|R$ -translation (Lecture 8...)

If

$$\|\Phi(\mathbf{y}) - \Phi^p(\mathbf{y})\| < \epsilon,$$

then

$$\|(\mathcal{R}|\mathcal{R})(\mathbf{t})(\Phi(\mathbf{y}) - \Phi^p(\mathbf{y}))\| = \|(\mathcal{R}|\mathcal{R})(\mathbf{t})\| \|\Phi(\mathbf{y}) - \Phi^p(\mathbf{y})\| < \epsilon,$$

$$\|(\mathcal{S}|\mathcal{S})(\mathbf{t})(\Phi(\mathbf{y}) - \Phi^p(\mathbf{y}))\| = \|(\mathcal{S}|\mathcal{S})(\mathbf{t})\| \|\Phi(\mathbf{y}) - \Phi^p(\mathbf{y})\| < \epsilon,$$

$$\|(\mathcal{S}|\mathcal{R})(\mathbf{t})(\Phi(\mathbf{y}) - \Phi^p(\mathbf{y}))\| = \|(\mathcal{S}|\mathcal{R})(\mathbf{t})\| \|\Phi(\mathbf{y}) - \Phi^p(\mathbf{y})\| < \epsilon.$$

# Example Problem

**Problem:**

Evaluate the MLFMM error for computation of function'

$$v(\mathbf{y}) = \sum_{k=0}^N u_k \Phi(\mathbf{y}, \mathbf{x}_k),$$

$$\Phi(\mathbf{y}, \mathbf{x}_k) = \frac{1}{\mathbf{y} - \mathbf{x}_k},$$

where  $\mathbf{y}$  and  $\mathbf{x}_k$  are points in a box of size  $D$  and space is subdivided by the binary tree to the maximum level  $L$ .

# From Lecture 6...

$$|y - x_*| < |x_i - x_*| :$$

↓ R-expansion

$$\Phi(y, x_i) = \sum_{m=0}^{\infty} a_m(x_i, x_*) R_m(y - x_*),$$

$$a_m(x_i, x_*) = -(x_i - x_*)^{-m-1}, \quad m = 0, 1, \dots,$$

$$R_m(y - x_*) = (y - x_*)^m, \quad m = 0, 1, \dots$$

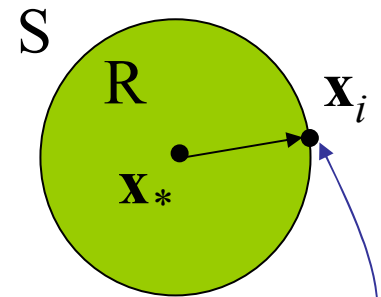
$$|y - x_*| > |x_i - x_*| :$$

↓ S-expansion

$$\Phi(y, x_i) = \sum_{m=0}^{\infty} b_m(x_i, x_*) S_m(y - x_*),$$

$$b_m(x_i, x_*) = (x_i - x_*)^m, \quad m = 0, 1, \dots,$$

$$S_m(y - x_*) = (y - x_*)^{-m-1}, \quad m = 0, 1, \dots$$



Singular Point is located at the Boundary of regions for the R- and S-expansions!

# From Lecture 8...

$$(|y - x_*| < |t|)$$

$$\begin{aligned} S_n(y - x_* + t) &= (t + y)^{-n-1} = \sum_{m=0}^{\infty} \frac{1}{m!} \frac{d^m S_n(t)}{dt^m} (y - x_*)^m \\ &= \sum_{m=0}^{\infty} \frac{1}{m!} \frac{d^m S_n(t)}{dt^m} R_m(y - x_*) = \sum_{m=0}^{\infty} (S|R)_{mn}(t) R_m(y - x_*). \end{aligned}$$

So

$$(S|R)_{mn}(t) = \frac{1}{m!} \frac{d^m S_n(t)}{dt^m} = \frac{(-1)^m (m+n)!}{m! n! t^{n+m+1}}.$$

$$(S|R)(t) = \begin{pmatrix} t^{-1} & t^{-2} & t^{-3} & \dots \\ -t^{-2} & -2t^{-3} & -3t^{-4} & \dots \\ t^{-3} & 3t^{-4} & 6t^{-5} & \dots \\ \dots & \dots & \dots & \dots \end{pmatrix}$$

