

*Computational Methods*  
CMSC/AMSC/MAPL 460

Eigenvalues and Eigenvectors

Ramani Duraiswami,  
Dept. of Computer Science

# Eigen Values of a Matrix

- Definition:
- A  $N \times N$  matrix  $\mathbf{A}$  has an eigenvector  $\mathbf{x}$  (non-zero) with corresponding eigenvalue  $\lambda$  if

$$\mathbf{Ax} = \lambda \mathbf{x}$$

- This means

$$\mathbf{Ax} - \lambda \mathbf{x} = 0 \qquad (\mathbf{A} - \lambda \mathbf{I}) \mathbf{x} = 0$$

- If a matrix vector product gives a zero vector, then either the vector is zero, or the matrix has zero determinant (is singular).
- Here this means  $\det(\mathbf{A} - \lambda \mathbf{I}) = 0$

# Left and Right Eigenvectors

- Right eigenvector of a matrix  $A$  is

$$Ax = \lambda x$$

- For a  $N \times N$  matrix we can also define a left matrix product

$$y^t A = \lambda y^t$$

- So if we have

$$y^t A = \lambda y^t$$

then  $y$  is a left eigenvector of  $A$

- If  $A$  is symmetric  $A = A^t$
- $(Ax)^t = x^t A^t = x^t A = (\lambda x)^t = \lambda x^t$
- So left and right eigenvectors of a symmetric matrix are the same

# Symmetric Matrices

- A matrix is symmetric if its transpose is equal to itself
- $\mathbf{A}$  is symmetric if  $\mathbf{A}^t = \mathbf{A}$  For a complex matrix  $\mathbf{A}^H = \mathbf{A}$
- Eigenvalues and Eigenvectors of a real symmetric (complex hermitian) matrix are real and eigenvectors are orthogonal.

# Characteristic Equation

- $A\mathbf{x} = \lambda \mathbf{x}$  can be written as

$$(A - \lambda I)\mathbf{x} = \mathbf{0}$$

which holds for  $\mathbf{x} \neq \mathbf{0}$ , so  $(A - \lambda I)$  is singular and

$$\det(A - \lambda I) = 0$$

- This is called the characteristic polynomial. If  $A$  is  $n \times n$  the polynomial is of degree  $n$  and so  $A$  has  $n$  eigenvalues, counting multiplicities.

## Example

$$A = \begin{pmatrix} 4 & 3 \\ 1 & 2 \end{pmatrix} \quad A - \lambda I = \begin{pmatrix} 4 - \lambda & 3 \\ 1 & 2 - \lambda \end{pmatrix}$$

$$\det(A - \lambda I) = 0 \quad \Rightarrow \quad (4 - \lambda)(2 - \lambda) - (1)(3) = 0$$

$$\lambda^2 - 6\lambda + 5 = 0 \quad \Rightarrow \quad (\lambda - 5)(\lambda - 1) = 0$$

- Hence the two eigenvalues are 1 and 5.

## Example (continued)

- Once we have the eigenvalues, the eigenvectors can be obtained by substituting back into  $(A - \lambda I)\mathbf{x} = \mathbf{0}$ .
- This gives eigenvectors  $(1 \ -1)^T$  and  $(1 \ 1/3)^T$
- Note that we can scale the eigenvectors any way we want.
- Determinant are not used for finding the eigenvalues of large matrices.

# Positive Definite Matrices

- A complex matrix  $A$  is *positive definite* if for every nonzero complex vector  $\mathbf{x}$  the quadratic form  $\mathbf{x}^H A \mathbf{x}$  is real and:

$$\mathbf{x}^H A \mathbf{x} > 0$$

where  $\mathbf{x}^H$  denotes the conjugate transpose of  $\mathbf{x}$  (i.e., change the sign of the imaginary part of each component of  $\mathbf{x}$  and then transpose).

# Eigenvalues of Positive Definite Matrices

- If  $A$  is positive definite and  $\lambda$  and  $\mathbf{x}$  are an eigenvalue/eigenvector pair, then:

$$A\mathbf{x} = \lambda \mathbf{x} \quad \mathbf{x}^H A \mathbf{x} = \lambda \mathbf{x}^H \mathbf{x}$$

- Since  $\mathbf{x}^H A \mathbf{x}$  and  $\mathbf{x}^H \mathbf{x}$  are both real and positive it follows that  $\lambda$  is real and positive.

# Properties of Positive Definite Matrices

- If  $A$  is a positive definite matrix then:
  - $A$  is nonsingular.
  - The inverse of  $A$  is positive definite.
  - Gaussian elimination can be performed on  $A$  without pivoting.
  - The eigenvalues of  $A$  are positive.

# Hermitian Matrices

- A square matrix for which  $A = A^H$  is said to be an *Hermitian* matrix.
- If  $A$  is real and Hermitian it is said to be *symmetric*, and  $A = A^T$ .
- Every Hermitian matrix is positive definite.
- Every eigenvalue of an Hermitian matrix is real.
- Different eigenvectors of an Hermitian matrix are orthogonal to each other, i.e., their scalar product is zero.

# Eigen Decomposition

- Let  $\lambda_1, \lambda_2, \dots, \lambda_n$  be the eigenvalues of the  $n \times n$  matrix  $A$  and  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  the corresponding eigenvectors.
- Let  $\Lambda$  be the diagonal matrix with  $\lambda_1, \lambda_2, \dots, \lambda_n$  on the main diagonal.
- Let  $X$  be the  $n \times n$  matrix whose  $j$ th column is  $\mathbf{x}_j$ .
- Then  $AX = X\Lambda$ , and so we have the *eigen decomposition* of  $A$ :

$$A = X\Lambda X^{-1}$$

- This requires  $X$  to be invertible, thus the eigenvectors of  $A$  must be linearly independent.

# Powers of Matrices

- If  $A = X^t \Lambda X^{-1}$  then:

$$A^2 = (X^t \Lambda X^{-1})(X^t \Lambda X^{-1}) = X^t \Lambda (X^{-1}X) \Lambda X^{-1} = X^t \Lambda^2 X^{-1}$$

Hence we have:

$$A^p = X^t \Lambda^p X^{-1}$$

- Thus,  $A^p$  has the same eigenvectors as  $A$ , and its eigenvalues are  $\lambda_1^p, \lambda_2^p, \dots, \lambda_n^p$ .
- We can use these results as the basis of an iterative algorithm for finding the eigenvalues of a matrix.

# The Power Method

- Label the eigenvalues in order of decreasing absolute value so  $|\lambda_1| > |\lambda_2| > \dots > |\lambda_n|$ .

- Consider the iteration formula:

$$\mathbf{y}_{k+1} = A\mathbf{y}_k$$

where we start with some initial  $\mathbf{y}_0$ , so that:

$$\mathbf{y}_k = A^k \mathbf{y}_0$$

- Then  $\mathbf{y}_k$  converges to the eigenvector  $\mathbf{x}_1$  corresponding the eigenvalue  $\lambda_1$ .

# Proof

- We know that  $A^k = X \Lambda^k X^{-1}$ , so:

$$\mathbf{y}_k = A^k \mathbf{y}_0 = X \Lambda^k X^{-1} \mathbf{y}_0$$

- Now we have:

$$\Lambda^k = \begin{pmatrix} \lambda_1^k & & & \\ & \lambda_2^k & & \\ & & \ddots & \\ & & & \lambda_n^k \end{pmatrix} = \lambda_1^k \begin{pmatrix} 1 & & & \\ & \lambda_2^k / \lambda_1^k & & \\ & & \ddots & \\ & & & \lambda_n^k / \lambda_1^k \end{pmatrix}$$

- The terms on the diagonal get smaller in absolute value as  $k$  increases, since  $\lambda_1$  is the dominant eigenvalue.

## Proof (continued)

- So we have

$$y_k = \lambda_1^k \begin{pmatrix} \vdots & & \vdots \\ x_1 & \cdots & x_n \\ \vdots & & \vdots \end{pmatrix} \begin{pmatrix} 1 & & & \\ & 0 & & \\ & & \ddots & \\ & & & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} = \lambda_1^k c_1 x_1$$

- Since  $\lambda_1^k c_1 \mathbf{x}_1$  is just a constant times  $\mathbf{x}_1$  then we have the required result.

# Example

- Let  $A = \begin{bmatrix} 2 & -12 \\ 1 & -5 \end{bmatrix}$  and  $\mathbf{y}_0 = \begin{bmatrix} 1 & 1 \end{bmatrix}'$
- $\mathbf{y}_1 = -4 \begin{bmatrix} 2.50 & 1.00 \end{bmatrix}'$
- $\mathbf{y}_2 = 10 \begin{bmatrix} 2.80 & 1.00 \end{bmatrix}'$
- $\mathbf{y}_3 = -22 \begin{bmatrix} 2.91 & 1.00 \end{bmatrix}'$
- $\mathbf{y}_4 = 46 \begin{bmatrix} 2.96 & 1.00 \end{bmatrix}'$
- $\mathbf{y}_5 = -94 \begin{bmatrix} 2.98 & 1.00 \end{bmatrix}'$
- $\mathbf{y}_6 = -190 \begin{bmatrix} 2.99 & 1.00 \end{bmatrix}'$
- The iteration is converging on a scalar multiple of  $\begin{bmatrix} 3 & 1 \end{bmatrix}'$ , which is the correct dominant eigenvector.

# Rayleigh Quotient

- Note that once we have the eigenvector, the corresponding eigenvalue can be obtained from the *Rayleigh quotient*:

$$\text{dot}(\mathbf{A}\mathbf{x}, \mathbf{x}) / \text{dot}(\mathbf{x}, \mathbf{x})$$

where  $\text{dot}(\mathbf{a}, \mathbf{b})$  is the scalar product of vectors  $\mathbf{a}$  and  $\mathbf{b}$  defined by:

$$\text{dot}(\mathbf{a}, \mathbf{b}) = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$$

- So for our example,  $\lambda_1 = -2$ .

# Scaling

- The  $\lambda_1^k$  can cause problems as it may become very large as the iteration progresses.
- To avoid this problem we scale the iteration formula:

$$\mathbf{y}_{k+1} = A(\mathbf{y}_k / r_{k+1})$$

where  $r_{k+1}$  is the component of  $A\mathbf{y}_k$  with largest absolute value.

# Example with Scaling

- Let  $A = [2 \ -12; 1 \ -5]$  and  $\mathbf{y}_0 = [1 \ 1]'$
- $A\mathbf{y}_0 = [-10 \ -4]'$  so  $r_1 = -10$  and  $\mathbf{y}_1 = [1.00 \ 0.40]'$ .
- $A\mathbf{y}_1 = [-2.8 \ -1.0]'$  so  $r_2 = -2.8$  and  $\mathbf{y}_2 = [1.0 \ 0.3571]'$ .
- $A\mathbf{y}_2 = [-2.2857 \ -0.7857]'$  so  $r_3 = -2.2857$  and  $\mathbf{y}_3 = [1.0 \ 0.3437]'$ .
- $A\mathbf{y}_3 = [-2.1250 \ -0.7187]'$  so  $r_4 = -2.1250$  and  $\mathbf{y}_4 = [1.0 \ 0.3382]'$ .
- $A\mathbf{y}_4 = [-2.0588 \ -0.6912]'$  so  $r_5 = -2.0588$  and  $\mathbf{y}_5 = [1.0 \ 0.3357]'$ .
- $A\mathbf{y}_5 = [-2.0286 \ -0.6786]'$  so  $r_6 = -2.0286$  and  $\mathbf{y}_6 = [1.0 \ 0.3345]'$ .
- $r$  is converging to the correct eigenvector  $-2$ .

# Scaling Factor

- At step  $k+1$ , the scaling factor  $r_{k+1}$  is the component with largest absolute value is  $A\mathbf{y}_k$ .
- When  $k$  is sufficiently large  $A\mathbf{y}_k \simeq \lambda_1 \mathbf{y}_k$ .
- The component with largest absolute value in  $\lambda_1 \mathbf{y}_k$  is  $\lambda_1$  (since  $\mathbf{y}_k$  was scaled in the previous step to have largest component 1).
- Hence,  $r_{k+1} \rightarrow \lambda_1$  as  $k \rightarrow \infty$ .

# MATLAB Code

```
function [lambda,y]=powerMethod(A,y,n)
for (i=1:n)
    y = A*y;
    [c j] = max(abs(y));
    lambda = y(j);
    y = y/lambda;
end
```

# Convergence

- The Power Method relies on us being able to ignore terms of the form  $(\lambda_j / \lambda_1)^k$  when  $k$  is large enough.
- Thus, the convergence of the Power Method depends on  $|\lambda_2 / \lambda_1|$ .
- If  $|\lambda_2 / \lambda_1| = 1$  the method will not converge.
- If  $|\lambda_2 / \lambda_1|$  is close to 1 the method will converge slowly.

# Orthonormal Vectors

- A set  $S$  of nonzero vectors are *orthonormal* if, for every  $\mathbf{x}$  and  $\mathbf{y}$  in  $S$ , we have  $\text{dot}(\mathbf{x}, \mathbf{y}) = 0$  (orthogonality) and for every  $\mathbf{x}$  in  $S$  we have  $\|\mathbf{x}\|_2 = 1$  (length is 1).

# The QR Algorithm

- The QR algorithm for finding eigenvalues is based on the QR factorisation that represents a matrix  $A$  as:

$$A = QR$$

where  $Q$  is a matrix whose columns are orthonormal, and  $R$  is an upper triangular matrix.

- Note that  $Q^H Q = I$  and  $Q^{-1} = Q^H$ .
- $Q$  is termed a *unitary* matrix.

# QR Algorithm without Shifts

$$A_0 = A$$

for  $k=1,2,\dots$

$$Q_k R_k = A_k$$

$$A_{k+1} = R_k Q_k$$

end

Since:

$$A_{k+1} = R_k Q_k = Q_k^{-1} A_k Q_k$$

then  $A_k$  and  $A_{k+1}$  are similar and so have the same eigenvalues.

$A_{k+1}$  tends to an upper triangular matrix with the same eigenvalues as  $A$ . These eigenvalues lie along the main diagonal of  $A_{k+1}$ .

# QR Algorithm with Shift

```
A0 = A
for k=1,2,...
  s = Ak(n,n)
  QkRk = Ak - sI
  Ak+1 = RkQk + sI
end
```

Since:

$$\begin{aligned}A_{k+1} &= R_k Q_k + sI \\ &= Q_k^{-1}(A_k - sI)Q_k + sI \\ &= Q_k^{-1}A_k Q_k\end{aligned}$$

so once again  $A_k$  and  $A_{k+1}$  are similar and so have the same eigenvalues.

The shift operation subtracts  $s$  from each eigenvalue of  $A$ , and speeds up convergence.

# MATLAB Code for QR Algorithm

- Let A be an  $n \times n$  matrix

```
n = size(A,1);
```

```
I = eye(n,n);
```

```
s = A(n,n); [Q,R] = qr(A-s*I); A = R*Q+s*I
```

- Use the up arrow key in MATLAB to iterate or put a loop round the last line.

# Deflation

- The eigenvalue at  $A(n,n)$  will converge first.
- Then we set  $s=A(n-1,n-1)$  and continue the iteration until the eigenvalue at  $A(n-1,n-1)$  converges.
- Then set  $s=A(n-2,n-2)$  and continue the iteration until the eigenvalue at  $A(n-2,n-2)$  converges, and so on.
- This process is called *deflation*.