

***“Implementing an Interior Point Method for Linear Programs
on a CPU-GPU System”***

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Summary

Hidden inside your desktop or laptop computer is a very powerful parallel processor, the graphics processing unit (GPU). This hardware is dedicated to rendering images on your screen, and its design was driven by the demands of the gaming industry. These processors are freely-available and potentially powerful computational engines that can be used with the host central processing unit (CPU) to solve numerical problems. We present a CPU-GPU algorithm for solving linear programming problems using interior point methods. Comparisons with a CPU implementation demonstrate that we can improve performance by using the GPU for sufficiently large problems. Since GPU architectures and programming languages are rapidly evolving, we expect that GPUs will be an increasingly attractive tool for matrix computation in the future.

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Originally, GPUs were much slower than CPUs and had very limited programmability. Now they show superior performance on some applications, and their speed is increasing at a rate faster than Moore's law predictions for CPUs.

The key to using GPUs for matrix computations lies in mapping matrix operations to shapes that the GPU can define. We use a rectangular-packed format to store lower triangular matrices, as shown in Figure 1. This makes computations such as the product of a matrix times its transpose easy to perform. Using this storage scheme, we can use the GPU to very quickly form the product of a matrix with its transpose and then compute the lower triangular factor of the resulting matrix. These operations

form the core of the interior point method for solving linear programming problems. By comparing our implementations with a CPU implementation, we demonstrated that we can improve performance by using the GPU for sufficiently large problems.

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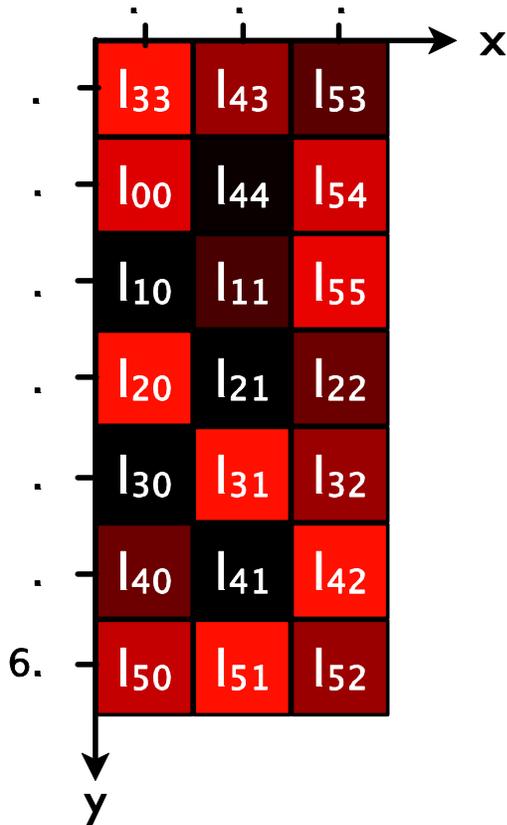


Figure 1. Storage of a lower triangular matrix in a texture using a packed storage scheme of Gunnels and Gustavson, with values stored as intensities of red. The 6×6 matrix is stored in a 3×7 texture, with the entries arranged as indicated.

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